

# The Orbit Equivalence Class of The Non-Singular Shift

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# Product measures

## Definition (product measures)

A probability measure  $\mu$  on  $2^{\mathbb{Z}}$  is a **product measure** if the coordinates  $X_n$ ,  $n \in \mathbb{Z}$ , are independent w.r.t.  $\mu$ .

- A product measure is denoted  $\mu = \bigotimes_{n \in \mathbb{Z}} \mu_n$ .
- $\mu = \bigotimes_{n \in \mathbb{Z}} \mu_n$  is **regular** if there is  $\delta > 0$  s.t.  $\mu_n(a) \geq \delta$ .

## Theorem (Kakutani's dichotomy (48'))

If  $\mu = \bigotimes_{n \in \mathbb{Z}} \mu_n$  and  $\nu = \bigotimes_{n \in \mathbb{Z}} \nu_n$  are supported on the same cylinders, they are either equivalent or totally singular.

*Moreover:*  $\mu \sim \nu \iff \sum_{n \in \mathbb{Z}} \sum_a (\sqrt{\mu_n(a)} - \sqrt{\nu_n(a)})^2 < \infty$ .

# Markov measures I

## Definition (Markov measures)

A probability measure  $\mu$  on  $2^{\mathbb{Z}}$  is a **Markov measure** if for every  $n$ , conditionally on  $X_n$ , the mutual distribution of  $\dots, X_{n-2}, X_{n-1}$  is independent of  $X_{n+1}, X_{n+2}, \dots$ .

- A Markov measure is denoted  $\mu = \mu(P_n)_{n \in \mathbb{Z}}$  where  $(P_n)_{n \in \mathbb{Z}}$  is the stochastic matrix  $P_n(a, b) = \mu(X_{n+1} = b | X_n = a)$ .
- $\mu(P_n)_{n \in \mathbb{Z}}$  is **regular** if there is a positive integer  $M$  and  $\delta > 0$  s.t.  $\mu(X_{n+M} = b | X_n = a) = P_n \cdots P_{n+M}(a, b) \geq \delta$ .
- In order for the shift to be non-singular, all the matrices  $P_n$  need to share the same support. Thus, the support of a Markov measure is a sub-shift of finite type.

## Markov measures II

- Kakutani's dichotomy fails for general Markov measures.
- The reason is that Markov measures do not have tail 0-1 law.

### Theorem (A-R (22'))

**Regular** Markov measures  $\mu = \mu_{(P_n)_{n \in \mathbb{Z}}}$  and  $\nu = \nu_{(Q_n)_{n \in \mathbb{Z}}}$  are either equivalent or totally singular.

There is a quantitative criteria, generalizing Kakutani's criteria, to decide between these alternatives.

- The proof is purely probabilistic in nature.
- If  $\mu$  is a Markov measure on  $2^{\mathbb{Z}}$ , the push-forward of  $\mu$  by the shift is again a Markov measure.

# Recap I

- $(X, \mu)$  is a standard non-atomic measure space.
- $\text{Aut}(X, [\mu])$  is the group of invertible transformations  $T : X \rightarrow X$  s.t.  $\mu$  and  $\mu \circ T$  are equivalent.
- For  $T \in \text{Aut}(X, [\mu])$  the R-N cocycle is  $\psi_T(x) = \log \frac{d\mu \circ T}{d\mu}(x)$ .
- A **non-singular action**  $G \curvearrowright (X, \mu)$  is a group-homomorphism  $G \rightarrow \text{Aut}(X, [\mu])$ .

**Ergodicity:**  $G \curvearrowright (X, \mu)$  is **ergodic** if every set  $A \subset X$  with  $G.A \subset A$  satisfies  $\mu(A) = 0$  or  $\mu(X \setminus A) = 0$ .

**Recurrence:**  $G \curvearrowright (X, \mu)$  is **recurrent** if for every set  $A \subset X$  there is a  $g \in G$  s.t.  $\mu(A \cap g.A) > 0$ .

## Recap II

- $G \curvearrowright (X, \mu)$  is a non-singular action.
- $r \in \mathbb{R}$  is an **essential value** if for  $A \subset X$  and  $\epsilon > 0$ , there is a scheme  $g : B \rightarrow g(B)$  in  $A$  s.t.  $|\psi_g(x) - r| < \epsilon$  for  $x \in B$ .
- The **ratio set**  $\text{RatioSet}(G, \mu) \subset \mathbb{R}$  is the closed subgroup of all essential values.
- Then the ratio set is either of the following:  
 $\{0\}$  (Type III<sub>0</sub>),  $\mathbb{Z} \log \lambda$  (Type III <sub>$\lambda$</sub> ),  $\mathbb{R}$  (Type III<sub>1</sub>).
- For amenable groups, the ratio set is a complete invariant of o.e. (outside the notorious Type III<sub>0</sub>).

## The orbit equivalence class of the shift II

Theorem (Bjorklund, Kosloff & Vaes (21'); A-R (22'))

*The only possible o.e. classes for regular Markov shift are Type II and Type III<sub>1</sub>.*

*Moreover: Type II occurs iff  $\mu$  is equivalent to a stationary Markov measure ( $P_n = P$  for all  $n$ ).*

- The exact classification of the shift was completely unknown until the last decade.
- Before that, only specific constructions of Bernoulli shifts of Type III were known, but not the exact Type III <sub>$\lambda$</sub> .

Corollary

*The only way in which a regular Markov shift is probability preserving, is when it is a classical stationary Markov chain.*



# The orbit equivalence class of the shift III

- If  $\mu = \mu(P_n)_{n \in \mathbb{Z}}$  is a Markov shift,

$$\psi_n(x) = \log \frac{d\mu \circ T^n}{d\mu}(X) = \log \prod_{k \in \mathbb{Z}} \frac{P_{k-n}(x_k, x_{k+1})}{P_k(x_k, x_{k+1})}.$$

- Outside certain examples, this is extremely complicated.

## Theorem (A-R (22'))

If  $\mu$  is a regular Markov shift,  $\text{RatioSet}(\Pi, \mu) \subset \text{RatioSet}(T, \mu)$ .

- In this formulation, “ $\Pi$ ” stands for the non-singular modification of the finite permutations.



# The asymptotic group I

## Definition

Let  $G \curvearrowright (X, \mu)$  be a non-singular action. Fix a compatible metric  $d$  on  $X$ . The **asymptotic group** to  $G$  is the class  $G'$  of all  $T \in \text{Aut}(X, [\mu])$  s.t.

- $d$ -asymptotic:  $d(g.x, g.Tx) \xrightarrow{g \rightarrow \infty} 0$  for almost every  $x \in X$ .
- $\mu$ -asymptotic:  $|\psi_g(x) - \psi_{g \circ T}(x)| \xrightarrow{g \rightarrow \infty} 0$  for almost every  $x \in X$ .

- Using the triangle inequality (for  $d$ -asymptotic) and the cocycle property (for  $\mu$ -asymptotic), the asymptotic group is indeed a group.
- In general, no containment relations between  $G$  and  $G'$ .

# The asymptotic group II

Example ("  $E_0$ -actions are asymptotic to  $E(G, 2)$ -actions")

$X = 2^{\mathbb{Z}}$  with the metric  $d(x, y) = 2^{-\inf\{|n|: x_n \neq y_n\}}$  and  $G = \mathbb{Z}$  acting by shift.

- It is easy to see that  $\Pi$  is  $d$ -asymptotic to  $T$ .
- If  $\mu$  is a regular Bernoulli shift,  $\Pi$  is also  $\mu$ -asymptotic to  $T$ .
- If  $\mu$  is a regular Markov shift this is no longer true.
- However, there are enough elements of  $\Pi$  that are  $\mu$ -asymptotic to the shift.
- Thus,  $\Pi \cap G'$  is a rich group.

# The asymptotic group III

## Theorem (A-R (22'))

*Let  $G \curvearrowright (X, \mu)$  be a non-singular recurrent action of amenable group. For  $f : X \rightarrow \mathbb{C}$ , if  $f$  is  $G$ -invariant then it is  $G'$ -invariant.*

- *In particular, if  $G'$  is ergodic then  $G$  is ergodic.*
- The ratio set can be characterized using the invariant functions of the “Maharam extension”.
- Then  $e(G', \mu) \subset e(G, \mu)$  is a natural generalization of the above theorem.

# The asymptotic group IV (on the proof)

## Proof.

For simplicity assume  $G=\mathbb{Z}$  acts via  $T\in\text{Aut}(X,\mu)$  (measure preserving) and  $S$  is asymptotic to  $T$ .

- For  $f:X\rightarrow\mathbb{R}$  uniformly continuous,  $f(T^n x)-f(T^n(Sx))\xrightarrow{|n|\rightarrow\infty}0$ .
- By the ergodic theorem

$$\begin{aligned}\mathbb{E}(f|\text{Inv}(T))\circ S &= \lim_{N\rightarrow\infty} \frac{1}{N} \sum_{n=1}^N f(T^n(Sx)) \\ &= \lim_{N\rightarrow\infty} \frac{1}{N} \sum_{n=1}^N f(T^n x) = \mathbb{E}(f|\text{Inv}(T)).\end{aligned}$$

- Approximating in  $L^1$ , the same holds for integrable  $f$ .
- If  $f\circ T=f$  then  $f\circ S=\mathbb{E}(f|\text{Inv}(T))\circ S=\mathbb{E}(f|\text{Inv}(T))=f$ .



# The asymptotic group $V$ (on the proof)

- Same argument works for non-singular transformations using:

## Theorem (Hurewicz's ergodic theorem)

Let  $T \in \text{Aut}(X, [\mu])$  and set  $w_n(x) = \frac{d\mu \circ T^n}{d\mu}(x)$ . Then

$$\lim_{N \rightarrow \infty} \frac{\sum_{n=1}^N w_n(x) f(T^n x)}{\sum_{n=1}^N w_n(x)} \text{ exists for almost every } x \in X.$$

- For prob. preserving actions of amenable groups the ergodic theorem holds along Følner sequences (Lindenstrauss).
- However, for non-singular actions of general groups (even Abelian) the ergodic theorem fails.

## The asymptotic group VI (on the proof)

- Typically, an “ergodic theorem” for an action  $G \curvearrowright (X, \mu)$  is a statement of the following form:

$\exists F_n \uparrow G, \forall f$ , the ergodic averages of  $f$  along  $(F_n)$  converge.

- However, for the sake of the above argument one may relax this to the following weaker assertion:

$\forall f, \exists F_n \uparrow G$ , the ergodic averages of  $f$  along  $(F_n)$  converge.

- We call this weaker version **ad hoc ergodic theorem**.

### Theorem (Danilenko (19'))

*Every non-singular free action of an amenable group satisfies the ad hoc ergodic theorem.*



# The asymptotic group VII (on the proof)

- The proof of the ad hoc ergodic theorem relies on:
  - ①  $\mu$ -hyperfiniteness of actions of amenable groups (Connes, Feldman & Weiss + Slaman & Steel).
  - ② The martingale convergence theorem: if  $\mathcal{F}_n \uparrow \mathcal{F}$  are  $\sigma$ -algebras then  $\mathbb{E}(\cdot | \mathcal{F}_n) \rightarrow \mathbb{E}(\cdot | \mathcal{F})$ .
- This reasoning goes beyond amenable groups, since non-amenable groups admit hyper-finite actions.

# The asymptotic group VII (on the proof)

## Example

Let  $F_r$  be the free group of rank  $r \geq 2$  and  $F_r \curvearrowright (\partial F_r, \nu)$ .

- $\partial F_r$  is a sub-shift of finite type of  $\{s_1, \dots, s_r\}^\omega$  and  $\nu$  is a natural Markov measure.
- It is non-singular, recurrent, ergodic and Type III.
- Its orbit equivalence relation  $E_t$  is hyper-finite (Connes, Feldman & Weiss; Dougherty, Jackson & Kechris).
- This is true for every non-elementary hyperbolic group acting on its Gromov boundary with a Patterson-Sullivan measure.
- These actions are hyper-finite (Adams; Marquis & Sabok).



Thank you